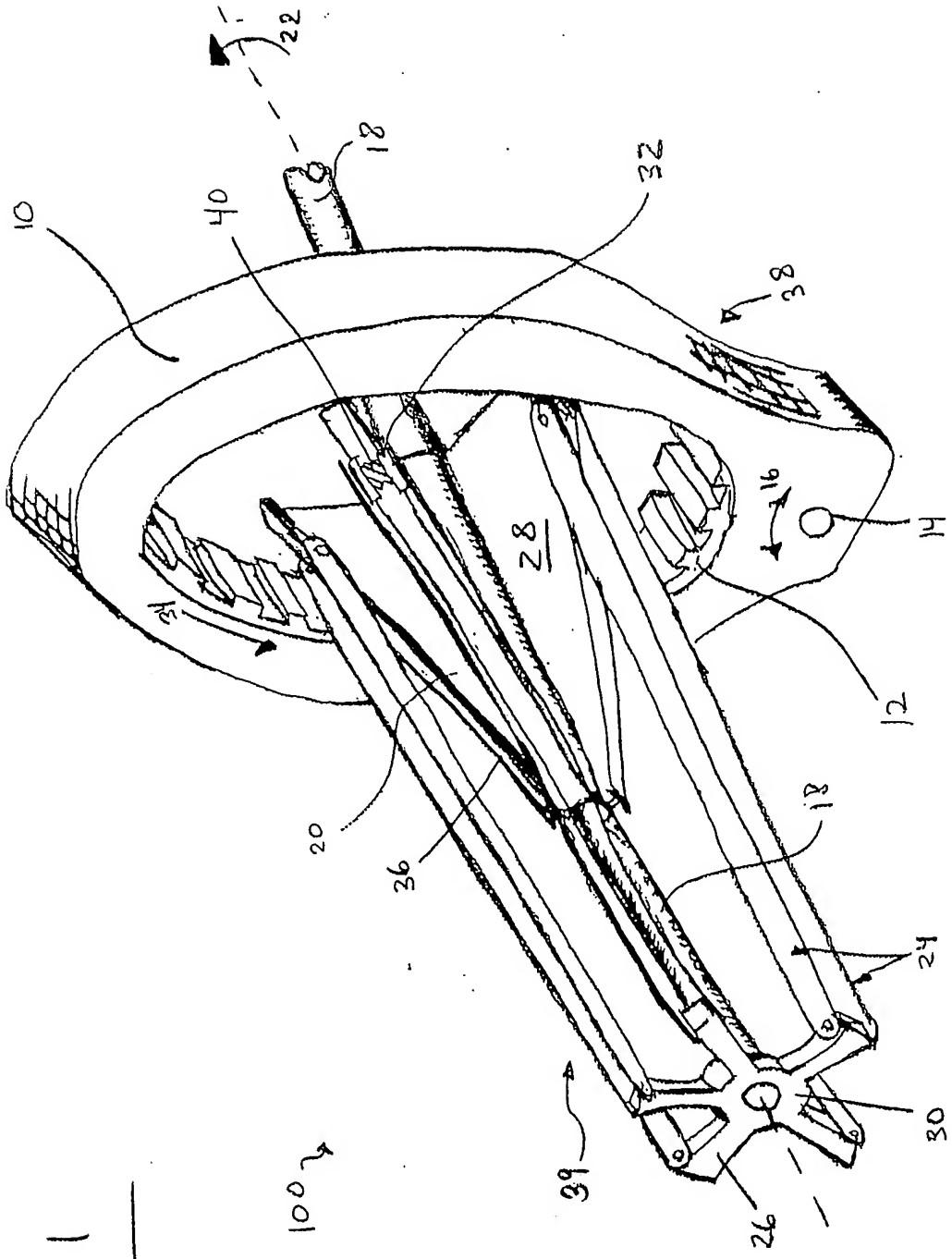


Fig. 1

Fig. 2

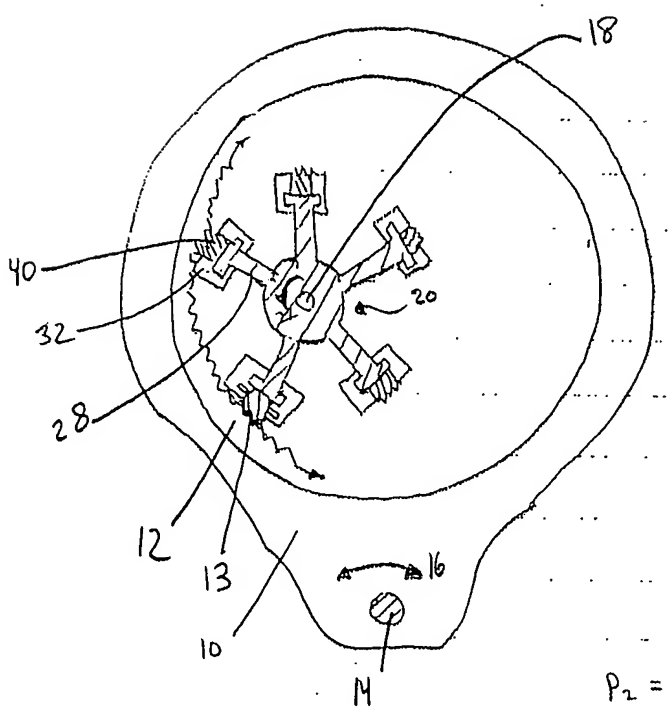
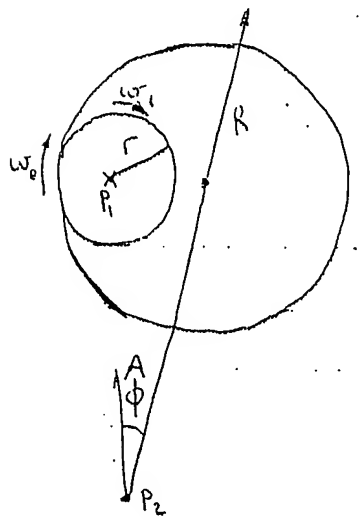


Fig. 2A



P_2 = Fixed in space

P_1 = Fixed point in space

$r = r(d)$ = variable radius

where d = displacement of cone

$\phi = \phi(d)$

ω_i = input angular velocity

ω_o = output angular velocity

A = angle of pivot ϕ

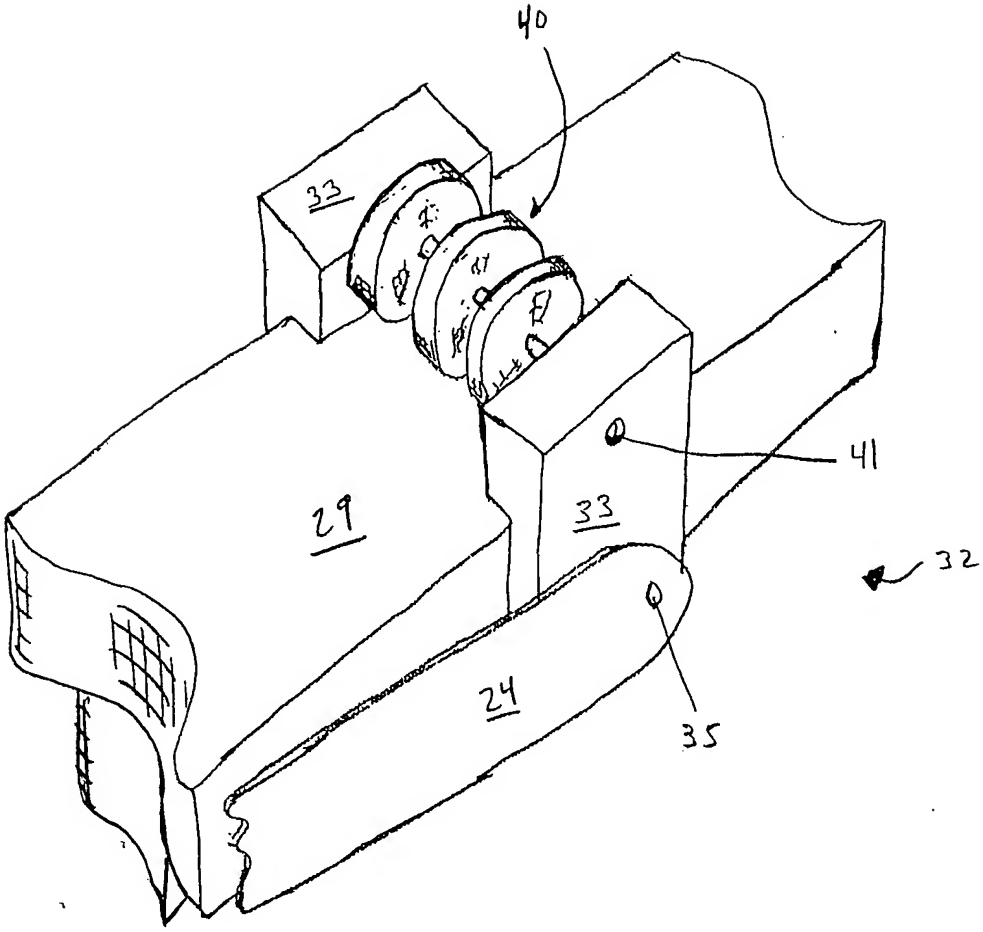


Fig. 3

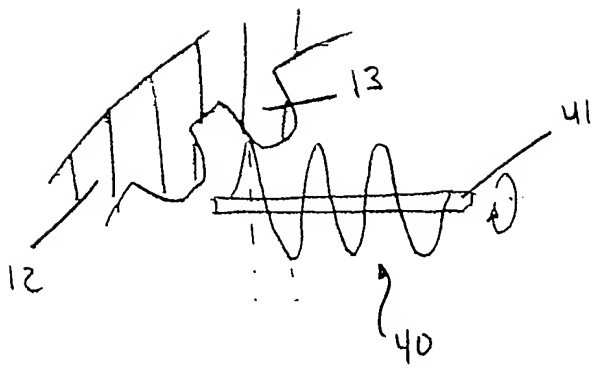


Fig. 3A

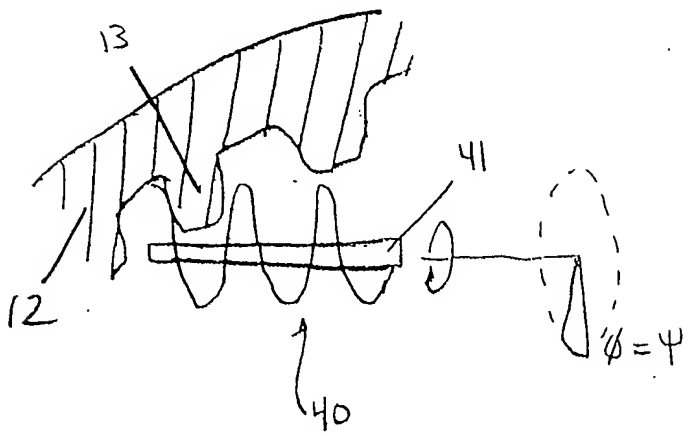


Fig. 3B

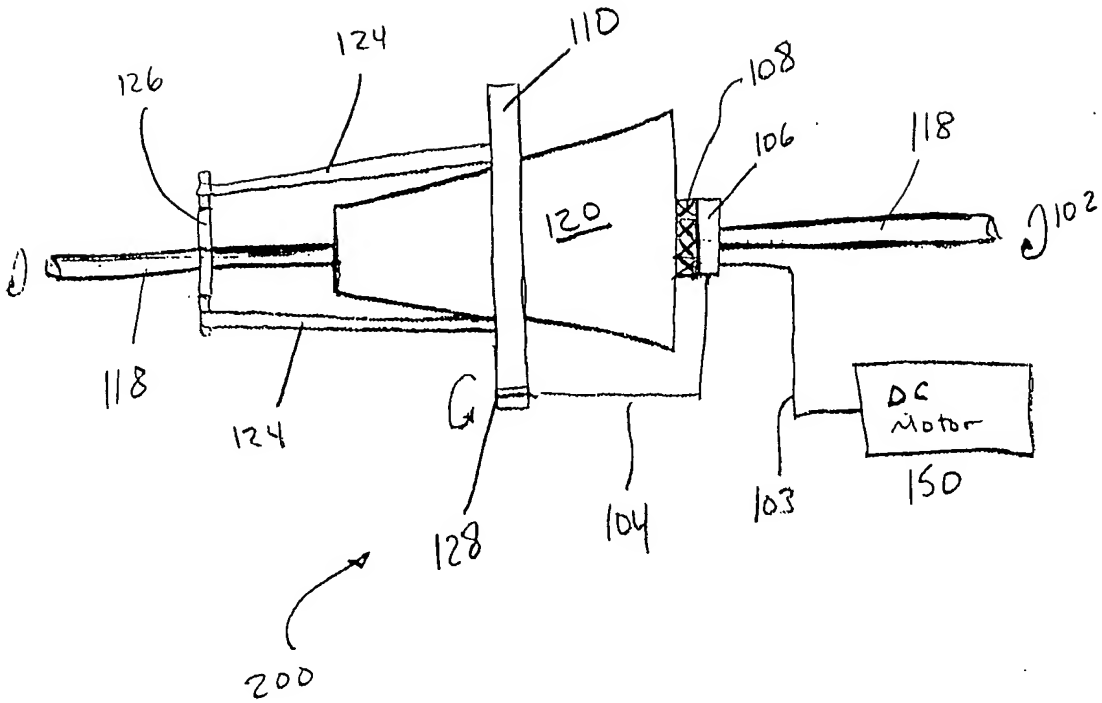


Fig. 4